## Computational Vision Psy 5036, Fall 2010 Study Guide

To prepare for the final, you need to read both the lecture notes and the relevant readings.

**Definitions of key concepts.** You will be asked to write a short paragraph on each concept discussing its definition and relationship to vision. On the exam, you will answer 8 from a selection of 12. 3 points each for a total of 24 points.

Predictive coding
shape-from-shading
correspondence problem
Generalized bas-relief transform
aperture problem
Distributed vs. modular representation
Inverse optics
lightness normalization (or anchoring) problem
Perceptual "explaining away"
gradient descent
slant/tilt
subjective contours
Bayes net
intersection of constraints

motion parallax
specular reflection
motion field vs. optic flow
homogeneous coordinates
structure-from-motion
gradient space (p,q)
Lightness/reflectance
lambertian
random dot stereogram
accidental view and generic view
motion gradient constraint
contrast normalization
pictorial cues
"features of intermediate complexity"

**Long essay questions.** On the exam, you will be asked to answer 2 questions. 12 points each for a total of 24 points for this section.

- 1. Sketch the connections between V1, V2, V4, MT, MST. Then pick one of these visual cortical areas and describe its properties and discuss its possible function(s).
- 2. Explain how the motion gradient constraint could be represented in terms of spatio-temporal neural receptive fields.
- 3. Discuss an algorithm for the computation of lightness. What are the limitations of spatial filter-type models for lightness?
- 4. Can all the parameters of the eye or camera's movement in a rigid environment be recovered from the motion field? Explain. Describe one method for recovering the translational component of camera motion from optic flow to determine direction of heading.
- 5. Describe the Bayesian decision theory approach to visual perception. Discuss its relation to the psychology and neurophysiology of perception.
- 6. Discuss the computational problems of visual object recognition. Explain the difference between "structural description" and image-based (or "exemplar") theories.
  - 7. Summarize and discuss the key points from one of the following papers on your reading list:
  - a) von der Heydt (2003)
  - b) Ullman et al. (2002)
  - c) Serre et al. (2007)
  - d) Weiss et al. (2002)
  - e) Green, Pouget & Bavelier (2010))
  - f) Torralba et al. (2006)
  - g) Grill-Spector (2003)
  - h) Heeger and Bergen (1995)
  - i) Singh & Fulvio (2007)